Equilibriums and Mixing Time in Open Quantum Systems

Gengzhi Yang

December 23, 2024

The mixing time of an open quantum system is an important question. Previous literature often relies on estimating the spectral gap of the Lindbladian generator. A recent interesting work [2] proposed a theoretical framework of obtaining the mixing time, without relying on the estimation of the spectral gap, based on several assumptions. Here I reviewed some related mathematical concepts in functional analysis and discussed the high-level ideas in [2].

1 A Brief Review of Dual Space

In this section the materials are mainly re-organized from wikipedia [1, 3, 5].

Definition 1 (Dual Space). Given any vector space V over a field F, the dual space is defined V^* as the set of all linear maps $\phi: V \to F$. The dual space V^* itself becomes a vector space over F:

$$\begin{aligned} (\phi + \psi)(x) &= \phi(x) + \psi(x), \\ (a\phi)(x) &= a\phi(x). \end{aligned} \tag{1}$$

Here $x \in V$, ϕ, ψ are in V^* and $a \in F$.

Definition 2 (Algebraic Adjoint). Let X^* denote the dual space of a vector space X, and Y^* is the dual space of a vector space Y. If $u: X \to Y$ is a linear map, then its adjoint map $u^*: Y^* \to X^*$ is defined as $u^*f = fu$, where $f \in Y^*$. This can also be characterized as

$$\langle u^*f, x \rangle = \langle f, ux \rangle, \tag{2}$$

where $x \in X$ and $ux \in Y$.

For some matrix $A \in \mathbb{C}^{m \times n}$, $x \in \mathbb{C}^n$, $y \in \mathbb{C}^m$, take the usual inner product in the complex domain, we have

$$\langle Ax, y \rangle = (Ax)^{\dagger} y = x^{\dagger} A^{\dagger} y = \langle x, A^{\dagger} y \rangle.$$
(3)

Thus it is easy to see that for a finite-dimensional linear map described as a matrix A, its adjoint is its conjugate transpose A^{\dagger} .

Now let us consider a Lindbladian master equation:

$$\frac{\mathrm{d}}{\mathrm{d}t}\rho = \mathcal{L}^*\rho,$$

$$\mathcal{L}^* = -\imath[H,(\cdot)] + \sum_j [V_j(\cdot), V_j^{\dagger}] + [V_j,(\cdot)V_j^{\dagger}].$$
(4)

Here ρ is some density operator in a vector space X. For some observable A, we can view A as a member in X^* , where

$$\langle A, \rho \rangle := A(\rho) = \operatorname{Tr}(A\rho).$$
 (5)

Consider L^* as a linear map that maps from X to X, then its adjoint L maps an observable to another observable, defined as

$$\mathcal{L} = \imath [H, (\cdot)] + \sum_{j} [V_{j}^{\dagger}(\cdot), V_{j}] + [V_{j}^{\dagger}, (\cdot)V_{j}] = \mathcal{H} + \mathcal{D},$$
(6)

which is simply the conjugate transpose of L^* . Thus the adjoint dynamics is

$$\frac{\mathrm{d}}{\mathrm{d}t}A = \mathcal{L}A.\tag{7}$$

Not let us re-consider Equation 5.

$$\langle e^{\mathcal{L}t}A, \rho \rangle = \langle A, e^{\mathcal{L}^* t} \rho \rangle.$$
(8)

This inspired us that if $e^{\mathcal{L}^* t} \rho$ goes to its equilibrium σ ,

$$\lim_{t \to \infty} \langle e^{\mathcal{L}t} A, \rho \rangle = \lim_{t \to \infty} \langle A, e^{L^* t} \rho \rangle = \langle A, \sigma \rangle = \langle A, e^{\mathcal{L}^* \tau} \sigma \rangle = \langle e^{\mathcal{L}\tau} A, \sigma \rangle.$$
(9)

Again make τ goes to infinity, we can see the limit of $e^{\mathcal{L}t}A$ should be $\operatorname{Tr}(A\sigma)\mathbb{I}$, because of the arbitrary choice of ρ . We can foresee that the speed of $e^{\mathcal{L}t}A$ goes to $\operatorname{Tr}(A\sigma)\mathbb{I}$ could be used to quantify the speed of $e^{\mathcal{L}^*t}\rho$ goes to σ .

Remark 3 ([4]). For a CPTP map ϕ , its adjoint ϕ^* is unital, i.e. $\phi^*(\mathbb{I}) = \mathbb{I}$. It is worth noting that actually for any $k\mathbb{I}$, $\phi^*(k\mathbb{I}) = k\mathbb{I}$.

2 High-level Overview of the Estimation

As I stated before, now we turn to quantify the speed of $e^{\mathcal{L}t}A$ goes to $\operatorname{Tr}(A\sigma)\mathbb{I}$. Given the GNS inner-product defined as

$$\langle A, B \rangle_{\text{GNS}} := \text{Tr} \left(\sigma A^{\dagger} B \right).$$
 (10)

Note here in the original paper [2], they are stating an equilibrium \mathbb{I} . So the distance between A and the equilibrium $\text{Tr}(A\sigma)\mathbb{I}$ is

$$\mathcal{A} := A - \frac{\langle A, \operatorname{Tr}(A\sigma)\mathbb{I} \rangle_{\mathrm{GNS}}}{\langle \operatorname{Tr}(A\sigma)\mathbb{I}, \operatorname{Tr}(A\sigma)\mathbb{I} \rangle_{\mathrm{GNS}}} \operatorname{Tr}(A\sigma)\mathbb{I} = A - \operatorname{Tr}(A\sigma)\mathbb{I}.$$
(11)

Remark 4. This can also be easily understood as the difference between the starting point and its equilibrium.

An important property here is that $\operatorname{Tr}(\mathcal{A}\sigma) = 0$. Consider the set of Hermitian operators $\mathcal{S}_{\mathcal{A}} := {\mathcal{A} : \operatorname{Tr}(\mathcal{A}\sigma) = 0}$, we are hoping that $e^{\mathcal{L}t}$ damps any element in $\mathcal{S}_{\mathcal{A}}$. If this holds true,

$$\begin{aligned} \left\| e^{\mathcal{L}^{*}t} \rho - \sigma \right\|_{1} &= \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \operatorname{Tr} \left(A(e^{\mathcal{L}^{*}t} \rho - \sigma) \right) = \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \operatorname{Tr} \left(Ae^{\mathcal{L}^{*}t} \rho - A\sigma \right) \\ &= \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \operatorname{Tr} \left(Ae^{\mathcal{L}^{*}t} \rho \right) - \operatorname{Tr} \left(A\sigma \right) = \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \langle A, e^{\mathcal{L}^{*}t} \rho \rangle - \operatorname{Tr} \left(A\sigma \right) \\ &= \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \langle e^{\mathcal{L}t} A, \rho \rangle - \operatorname{Tr} \left(A\sigma \right) = \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \langle e^{\mathcal{L}t} \left(A - \operatorname{Tr} \left(A\sigma \right) \mathbb{I} \right), \rho \rangle + \operatorname{Tr} \left(A\sigma \right) - \operatorname{Tr} \left(A\sigma \right) \\ &= \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \langle e^{\mathcal{L}t} \left(A - \operatorname{Tr} \left(A\sigma \right) \mathbb{I} \right), \rho \rangle = \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \operatorname{Tr} \left(e^{\mathcal{L}t} \left(A - \operatorname{Tr} \left(A\sigma \right) \mathbb{I} \right) \rho \right) \\ &= \sup_{-\mathbb{I} \leq A \leq \mathbb{I}} \operatorname{Tr} \left(\sigma \sigma^{-1} \rho e^{\mathcal{L}t} \left(A - \operatorname{Tr} \left(A\sigma \right) \mathbb{I} \right) \right) \\ &= \langle \sigma^{-1} \rho, e^{\mathcal{L}t} \left(A - \operatorname{Tr} \left(A\sigma \right) \mathbb{I} \right) \rangle_{\mathrm{GNS}} \leq \| \sigma^{-1} \rho \|_{\mathrm{GNS}} \| e^{\mathcal{L}t} \left(A - \operatorname{Tr} \left(A\sigma \right) \mathbb{I} \right) \|_{\mathrm{GNS}} \,. \end{aligned}$$
(12)

In fact, it is possible to have the theorem below:

Theorem 5 (Main result in [2]). Under certain conditions, there exists positive constants λ and C, such that for some Hermitian operator A satisfying $Tr(A\sigma) = 0$, we have

$$\left\|e^{\mathcal{L}t}A\right\|_{GNS} \le Ce^{-\lambda t} \left\|A\right\|_{GNS}.$$
(13)

Now we need to design the conditions needed to damp the elements in $\mathcal{S}_{\mathcal{A}}$. Take $A \in \mathcal{S}_{\mathcal{A}}$, define $A(t) = e^{t\mathcal{L}}A = e^{t(\mathcal{D}+\mathcal{H})}A$. Condiser $L(A(t)) := \frac{1}{2} ||A(t)||_{\text{GNS}}^2$, and its derivative is $-D(A(t)) := \frac{d}{dt}L(A(t)) = \frac{1}{2} \langle (\mathcal{D}+\mathcal{H})A(t), A(t) \rangle_{\text{GNS}} + \frac{1}{2} \langle A(t), (\mathcal{D}+\mathcal{H})A(t) \rangle_{\text{GNS}} = \Re \langle \mathcal{D}A(t), A(t) \rangle_{\text{GNS}}$.

We are hoping to show that $D(A(t)) \ge \kappa ||A(t)||_{\text{GNS}}$ for some positive κ , and this can be achieved by providing some assumptions on \mathcal{H} and \mathcal{D} . The details can be found in [2].

Remark 6. Actually one should use an equivalent norm of L(A) other than the exact L(A) itself to prove the desired properties.

References

- [1] Dual space. https://en.wikipedia.org/wiki/Dual_space.
- [2] Di Fang, Jianfeng Lu, and Yu Tong. "Mixing time of open quantum systems via hypocoercivity". In: arXiv preprint arXiv:2404.11503 (2024).
- [3] Functional. https://en.wikipedia.org/wiki/Functional_(mathematics).
- [4] Quantum channel. https://en.wikipedia.org/wiki/Quantum_channel.
- [5] Transpose of a linear map. https://en.wikipedia.org/wiki/Transpose_of_a_linear_map.